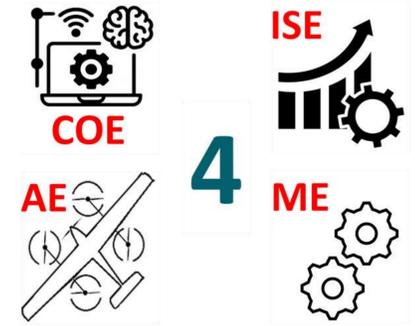


First-Aid Drone with Live Medical Assistance (FAD-LMA)

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Introduction

Problem Statement

There is a critical need for a rapid-response system like our FAD-LMA to deliver medical aid and live assistance to patients in hard-to-reach areas during emergencies.

Project Deliverables

- 1- Working First-Aid Drone
- 2- Drone stations optimization model

Constraints

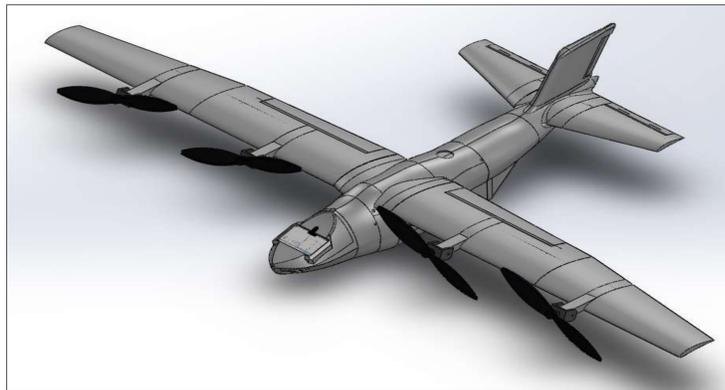
- Total weight: $\leq 15\text{kg}$
- Payload weight: $\leq 5\text{kg}$
- Project Duration: 90 days
- Budget: $\leq 8,000\text{ SAR}$
- Regulations: GACA UAV Category B & MOH clearance required

All specifications

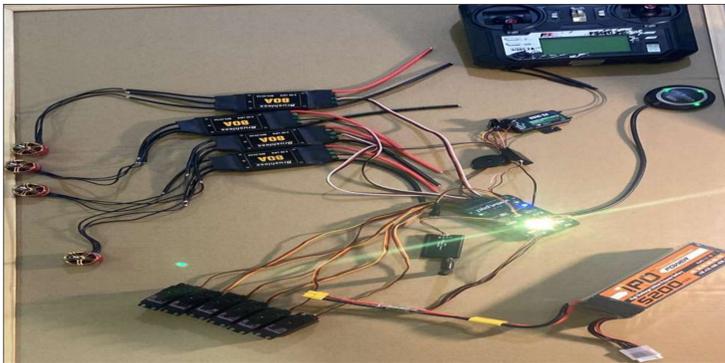
- Battery Power: 115 watts
- Speed: Can reach up to 60km/h
- Range: Can travel a distance of 13.5km
- Maximum Flight Duration: 13.5min
- Network Latency: should be $<200\text{ms}$
- Camera Quality: High-quality with 12MP
- Mic. Quality: Clear audio, $<65\text{dB SNR}$

Prototype Design

Structural Design (ME)



Control System (AE)



Communication (COE)

- Developed a doctor-patient communication system using Raspberry Pi.
- Integrated camera and microphone for audio/video interaction.
- Used a 4G module with a SIM card for internet access and phone calls.

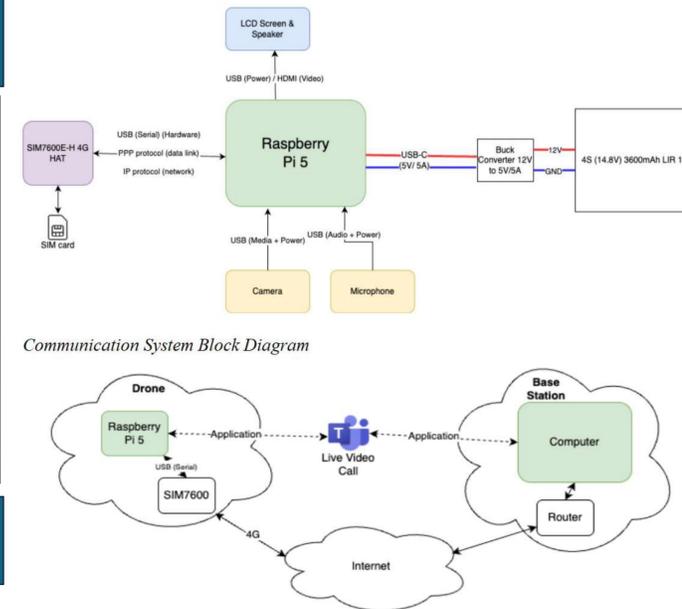


Figure 4 Video Call Communication

Drone stations optimization model

- Built an optimization model to optimize the number and locations of drone stations while meeting service level requirements.
- Applied the model in real scenarios using the professional open-source solver CBC.

User Inputs

- Enter area width
- Enter area Length
- Enter Area height if possible
- Enter Required drone speed
- Enter Maximum response time

System generated

- 500 random locations across specified area

Solution

Station Index	X	Y	Z (Altitude)
0	0	0	0.0
1	1	0	10.0
2	2	0	20.0

Optimization model

Objective function

$$\text{Minimize } Z = (1/P) \sum \sum (t_{ij} \times z_{ij})$$

Constraints

$$\sum z_{ij} = 1 \quad \forall i$$

$$d_{ij} * z_{ij} \leq R \quad \forall i, j$$

$$0 \leq x_j \leq L \quad \forall j, \quad 0 \leq y_j \leq W \quad \forall j$$

$$t_{ij} \times z_{ij} \leq 0.25 \quad \forall i, j$$

Process

System iterate on number of possibilities for stations number and locations till it find the configuration with the desired output

Verification and Testing

For the Propulsion and control (AE):

- All motors and propellers are matched to the specifications' quality.
- The control power system is proper to reach the best flight performance.

For the Structure (ME):

- Verify the mechanical components by supervising the manufacturing process to ensure all parts meet specifications.

For Communication System (COE):

- All components were installed and verified to ensure functionality.
- Camera and microphone confirmed via media capture.
- 4G module validated through connectivity and call tests.

For the stations optimization model (ISE):

- Verified outputs on small test cases.
- Tested model behaviour with extreme input values.
- Checked constraint satisfaction and objective consistency.

Conclusion

The VTOL medical drone effectively meets its objective by delivering essential medical kits to remote patients while enabling real-time communication with doctors, marking a significant step toward accessible healthcare.